Incompleteness Theorems for Observables in General Relativity

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This is joint work with Marios Christodoulou (IQOQI)



George Sparling (UPitt)



Table of Contents

1 Spacetimes



3 The Proof

4 Future Directions

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Let M be smooth 4-dimensional manifold. A Lorentzian metric on M is

"a symmetric and (1,3)-signature section g of the bundle $(TM \otimes TM)^* \to M$ "

 $g(\vec{V},\vec{W})_p:=$ the "inner product" of \vec{V},\vec{W} at $p\in M$



R. Penrose, "The Road to Reality"

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Incompleteness for Observables

Lorentzian metrics: concretely

A Lorentzian metric on \mathbb{R}^4 is given by a smooth map $g_{\mu\nu} \colon \mathbb{R}^4 \to \mathbb{R}^{4 \times 4}$

$$(x^{0}, x^{1}, x^{2}, x^{3}) \mapsto \begin{bmatrix} g_{00} & g_{01} & g_{02} & g_{03} \\ g_{10} & g_{11} & g_{12} & g_{13} \\ g_{20} & g_{21} & g_{22} & g_{23} \\ g_{30} & g_{31} & g_{32} & g_{33} \end{bmatrix}$$

with $g_{\mu\nu}$ being a symmetric, (-,+,+,+)-signature matrix. We have

 $g = g_{\mu\nu} \, dx^{\mu} dx^{\nu}$

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Example

If $\eta_{\mu\nu} := \begin{bmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$, then $\eta = -dt^2 + dx^2 + dy^2 + dz^2$

Einstein field equations

A spacetime is a Lorentzian metric $g_{\mu\nu} \colon \mathbb{R}^4 \to \mathbb{R}^{4 \times 4}$ which satisfies:

$$R_{\mu\nu} - \frac{1}{2}g_{\mu\nu}R = \frac{8\pi G}{c^4}T_{\mu\nu}$$
 (1)

for some "distribution of matter" given by the Stress-Energy tensor $T_{\mu\nu}$.

$$g_{\mu\nu} \rightsquigarrow \Gamma^{\rho}_{\mu\nu} \rightsquigarrow R^{\rho}_{\mu\sigma\nu} \rightsquigarrow R_{\mu\nu} \rightsquigarrow R$$

Compare to Poisson's equation for Newton's law of gravity:

$$\nabla^2 \varphi = 4\pi G \rho$$

Example

$$\begin{split} g_{\mu\nu} &:= 1/(2\omega^2) \big[-(dt+e^x dy)^2 + dx^2 + 1/2e^{2x} dy^2 + dz^2 \big] \\ T_{\mu\nu} &= \text{``rotating dust''} + \text{``negative cosmological constant''} \end{split}$$



Figure. Nmeti, Madarász, Andréka, Andai (after Hawking, Ellis)

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Question. Do $g_{\mu\nu}$ and $\tilde{g}_{\rho\sigma}$ represent different "geometries"?

$$g_{\mu\nu}\colon = \begin{bmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\widetilde{g}_{\rho\sigma} := \begin{bmatrix} -1 & -\cos(x_1) & 0 & 0\\ -\cos(x_1) & 1 - \cos^2(x_1) & 2x_2 & 0\\ 0 & 2x_2 & 4x_2^2 + 1 & -1\\ 0 & 0 & -1 & 2 \end{bmatrix}$$

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We say that $g_{\mu\nu}$ and $\tilde{g}_{\rho\sigma}$ are **diffeomorphic** and write $g_{\mu\nu} \simeq_{\text{diff}} \tilde{g}_{\rho\sigma}$ if there exists are smooth change of coordinates $\tilde{x}^{\xi} = \tilde{x}^{\xi}(x^{\eta})$ so that

$$g_{\mu\nu}(x^{\eta}) = \frac{\partial \widetilde{x}^{\rho}}{\partial x^{\mu}} \frac{\partial \widetilde{x}^{\sigma}}{\partial x^{\nu}} \widetilde{g}_{\rho\sigma}(\widetilde{x}^{\xi}) \text{ for all } x^{\eta}.$$

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Incompleteness for Observables

Same geometry, different coordinate system...

$$\begin{bmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \quad \mathsf{vs} \quad \begin{bmatrix} -1 & -\cos(\widetilde{x}_1) & 0 & 0 \\ -\cos(\widetilde{x}_1) & 1 - \cos^2(\widetilde{x}_1) & 2\widetilde{x}_2 & 0 \\ 0 & 2\widetilde{x}_2 & 4\widetilde{x}_2^2 + 1 & -1 \\ 0 & 0 & -1 & 2 \end{bmatrix}$$

Consider the change of coordinates $x_{\eta} = x_{\eta}(\widetilde{x}^{\xi})$ given by:

$$\begin{array}{rcl} x_0 = & \widetilde{x}_0 + \sin(\widetilde{x}_1) \\ x_1 = & \widetilde{x}_1 + \widetilde{x}_2^2 \\ x_2 = & \widetilde{x}_2 - \widetilde{x}_3 \\ x_3 = & \widetilde{x}_3 \end{array}$$

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Plug to
$$ds^2 = -(dx_0)^2 + (dx_1)^2 + (dx_2)^2 + (dx_3)^2$$

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An **observable** is any map $f: S \to R$ that is diffeomorphism invariant: for all $g_{\mu\nu}, \tilde{g}_{\rho\sigma} \in S$ we have $g_{\mu\nu} \simeq_{\text{diff}} \tilde{g}_{\rho\sigma} \implies f(g_{\mu\nu}) = f(\tilde{g}_{\rho\sigma})$

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Canonical Quantization Process

Step 1: Find **complete** set of observables for S.

Step 2: Promote them to an algebra of operators on a Hilbert space \mathcal{H} .

The problem of observables

"We define observables as functions (or functionals) of field variables that are invariant with respect to coordinate transformations." (1958) P.G. Bergmann, and A.I. Janis

"A program aiming at the identification and systematic exploitation of the observables has been under way for many years, but its execution is hampered by profound technical difficulties, which have not yet been overcome completely."

(1965) P.G. Bergmann,

"...presently we can give a formal characterization of observables in general relativity, but we are actually **not able to explicitly construct many examples** of quantities that satisfy it."

(2001) L. Smolin

"Observables for full general relativity (without special asymptotic symmetries or matter content) **almost certainly do not exist**." (2015) B. Dittrich, P. A. Höhn, T.A. Koslowski, and M.I. Nelson,

Examples of Observables

• Komar mass for static spacetimes

$$g_{\mu\nu} \mapsto \int_M (2T_{\mu\nu} - Tg_{\mu\nu}) u^\mu \xi^\nu \, dM$$

It is a complete observable for all Schwarzschild solutions



- ADM Observables for asymptotically flat spacetimes
- Coordinate-like Observables for spacetimes filled with "generic dust"

Theorem (P., Sparling, Christodoulou)

In the same way that "straightedge–and–compass" cannot construct $\sqrt[3]{2}$analysis cannot explicitly define complete observables"

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Assume that $S \supseteq S_{\emptyset}$ contains the collection of all vacuum solutions S_{\emptyset} . Then there is no observable $f: S \to R$ that is both Borel and complete.

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- $f: S \to R$ is **Borel** if it is Borel as a map from $S \subseteq C^{\infty}(\mathbb{R}^4, \mathbb{R}^{4 \times 4})$ endowed with the C^{∞} -compact-open topology to the Polish space R.

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Theorem (P., Sparling, Christodoulou)

"ZF+DC+no complete observables for $S \supseteq S_{\emptyset}$ exist" is consistent.

Table of Contents

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$$\alpha \simeq_{\mathbb{Z}} \beta \iff \exists k \in \mathbb{Z} \ \forall n \in \mathbb{Z} \ \alpha(n+k) = \beta(n)$$

i.e., the **orbit equivalence relation** of the *Bernoulli shift* $\mathbb{Z} \sim \{0,1\}^{\mathbb{Z}}$.

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There is **no Borel** map $f: \{0,1\}^{\mathbb{Z}} \to R$, taking values in Polish R, with

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Proof Sketch.

• Notice that $\mathbb{Z} \curvearrowright \{0,1\}^{\mathbb{Z}}$ has a dense orbit. This implies the "0–1 law": if $B \subseteq \{0,1\}^{\mathbb{Z}}$ is \mathbb{Z} -invariant and Borel, then one of B, B^c is comeager.

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• Assume f exists and get comeager $C\subseteq \{0,1\}^{\mathbb{Z}}$ so that $f(C)=\{x\}$



• Since \mathbb{Z} is countable, there exist $\alpha \not\simeq_{\mathbb{Z}} \beta$ in C. But $f(\alpha) = x = f(\beta)$

General Strategy

Let ${\mathcal S}$ be a collection of spacetimes.

In order to prove that:

"there is no observable $f: S \to R$ that is both **Borel & complete**"

it suffices to prove that:

there exists a **Borel reduction** from $(\{0,1\}^{\mathbb{Z}}, \simeq_{\mathbb{Z}})$ to $(\mathcal{S}, \simeq_{\text{diff}})$, i.e., a Borel map $r \colon \{0,1\}^{\mathbb{Z}} \to \mathcal{S}_{\emptyset}$ with $\alpha \simeq_{\mathbb{Z}} \beta \iff r(\alpha) \simeq_{\text{diff}} r(\beta)$

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Definition

S is **rich** if there exists a Borel reduction from $(\{0,1\}^{\mathbb{Z}}, \simeq_{\mathbb{Z}})$ to $(S, \simeq_{\text{diff}})$

Examples of Rich Families: part I

Theorem (Christodoulou, Sparling, P.)

For every $n \ge 2$, the family of all spacetimes on \mathbb{R}^n is rich.

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Source: Wikipedia

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Examples of Rich Families: part II

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Theorem (Christodoulou, Sparling, P.)

The family S_{\emptyset} of all vacuum solutions on \mathbb{R}^4 is rich.

Remark. There is a unique vacuum solution on \mathbb{R}^3 !

Proof: Plane Waves

Consider the variables u, v, x, y.

$$g^{H}_{\mu\nu}: \qquad (u,v,x,y) \mapsto \begin{bmatrix} H(u,x,y) & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Is a vacuum solution whenever $H_{xx} + H_{yy} = 0$.



Penrose: "A Remarkable Property of Plane Waves in General Relativity"

The reduction

For every $\alpha \in \{0,1\}^{\mathbb{Z}}$ we define a "smooth version" $w^{\alpha} \colon \mathbb{R} \to \mathbb{R}$ of α :



This defines a map $r \colon \{0,1\}^{\mathbb{Z}} \to \mathcal{S}_{\emptyset}$ which maps α to

$$r(\alpha) := g^{\alpha}_{\mu\nu} \quad \text{given by} \quad (u, v, x, y) \mapsto \begin{bmatrix} w^{\alpha}(u)xy & 1 & 0 & 0\\ 1 & 0 & 0 & 0\\ 0 & 0 & 1 & 0\\ 0 & 0 & 0 & 1 \end{bmatrix}$$

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• Showing that $\alpha E_{\mathbb{Z}}\beta \Rightarrow r(\alpha) \simeq_{\text{diff}} r(\beta)$ is easy.

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For every $\alpha \in \{0,1\}^{\mathbb{Z}}$ we define a "smooth version" $w^{\alpha} \colon \mathbb{R} \to \mathbb{R}$ of α :



This defines a map $r \colon \{0,1\}^{\mathbb{Z}} \to \mathcal{S}_{\emptyset}$ which maps α to

$$r(\alpha) := g^{\alpha}_{\mu\nu} \quad \text{given by} \quad (u, v, x, y) \mapsto \begin{bmatrix} w^{\alpha}(u)xy & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

- Showing that $\alpha E_{\mathbb{Z}}\beta \Rightarrow r(\alpha) \simeq_{\text{diff}} r(\beta)$ is easy.
- Showing that $\alpha E_{\mathbb{Z}}\beta \iff r(\alpha) \simeq_{\text{diff}} r(\beta)$ is hard.

The difficult direction

Assume that:

$$g := \left(\tilde{w}(\tilde{u})\tilde{x}\tilde{y}\right)d\tilde{u}^2 + 2d\tilde{u}d\tilde{v} + d\tilde{x}^2 + d\tilde{y}^2$$
$$\tilde{g} := \left(w(u)xy\right)du^2 + 2dudv + dx^2 + dy^2$$

are diffeomorphic under the smooth change of coordinates φ specified by

$$\begin{split} \tilde{u} &= \tilde{u}(u, v, x, y) \\ \tilde{v} &= \tilde{v}(u, v, x, y) \\ \tilde{x} &= \tilde{x}(u, v, x, y) \\ \tilde{y} &= \tilde{y}(u, v, x, y) \end{split}$$

$\label{eq:Goal:} \ensuremath{\mathsf{Goal}} \ensuremath{\mathsf{To}}$ show that w(u) is a $\mathbbm{Z}\text{-shift of }\tilde{w}(\tilde{u}).$

The difficult direction

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Goal:

To show that w(u) is a \mathbb{Z} -shift of $\tilde{w}(\tilde{u})$.

Naive approach: use the definition $g_{\mu\nu} = \frac{\partial \tilde{x}^{\rho}}{\partial x^{\mu}} \frac{\partial \tilde{x}^{\sigma}}{\partial x^{\nu}} \tilde{g}_{\rho\sigma}$

Dead end

The relation
$$g_{\mu\nu} = \frac{\partial \tilde{x}^{
ho}}{\partial x^{\mu}} \frac{\partial \tilde{x}^{\sigma}}{\partial x^{\nu}} \tilde{g}_{\rho\sigma}$$
 gives the following

$$\begin{array}{rcl} H(u,x,y) &=& \tilde{H}(\tilde{u},\tilde{x},\tilde{y})\tilde{u}_{u}+2\tilde{u}_{u}\tilde{v}_{u}+\tilde{x}_{u}^{2}+\tilde{y}_{u}^{2}\\ 0 &=& \tilde{H}(\tilde{u},\tilde{x},\tilde{y})\tilde{u}_{v}+2\tilde{u}_{v}\tilde{v}_{v}+\tilde{x}_{v}^{2}+\tilde{y}_{v}^{2}\\ 1 &=& \tilde{H}(\tilde{u},\tilde{x},\tilde{y})\tilde{u}_{x}+2\tilde{u}_{x}\tilde{v}_{x}+\tilde{x}_{x}^{2}+\tilde{y}_{x}^{2}\\ 1 &=& \tilde{H}(\tilde{u},\tilde{x},\tilde{y})\tilde{u}_{y}+2\tilde{u}_{y}\tilde{v}_{y}+\tilde{x}_{y}^{2}+\tilde{y}_{y}^{2}\\ 1 &=& 2\tilde{H}(\tilde{u},\tilde{x},\tilde{y})\tilde{u}_{u}\tilde{u}_{v}+2(\tilde{u}_{u}\tilde{v}_{v}+\tilde{u}_{v}\tilde{v}_{u})+2\tilde{x}_{u}\tilde{x}_{v}+2\tilde{y}_{u}\tilde{y}_{v}\\ 0 &=& 2\tilde{H}(\tilde{u},\tilde{x},\tilde{y})\tilde{u}_{u}\tilde{u}_{y}+2(\tilde{u}_{x}\tilde{v}_{y}+\tilde{u}_{y}\tilde{v}_{x})+2\tilde{x}_{u}\tilde{x}_{x}+2\tilde{y}_{u}\tilde{y}_{x}\\ 0 &=& 2\tilde{H}(\tilde{u},\tilde{x},\tilde{y})\tilde{u}_{u}\tilde{u}_{x}+2(\tilde{u}_{u}\tilde{v}_{x}+\tilde{u}_{x}\tilde{v}_{u})+2\tilde{x}_{u}\tilde{x}_{x}+2\tilde{y}_{u}\tilde{y}_{x}\\ 0 &=& 2\tilde{H}(\tilde{u},\tilde{x},\tilde{y})\tilde{u}_{u}\tilde{u}_{y}+2(\tilde{u}_{v}\tilde{v}_{y}+\tilde{u}_{y}\tilde{v}_{u})+2\tilde{x}_{v}\tilde{x}_{y}+2\tilde{y}_{u}\tilde{y}_{y}\\ 0 &=& 2\tilde{H}(\tilde{u},\tilde{x},\tilde{y})\tilde{u}_{v}\tilde{u}_{y}+2(\tilde{u}_{v}\tilde{v}_{x}+\tilde{u}_{x}\tilde{v}_{v})+2\tilde{x}_{v}\tilde{x}_{x}+2\tilde{y}_{v}\tilde{y}_{x}\\ 0 &=& 2\tilde{H}(\tilde{u},\tilde{x},\tilde{y})\tilde{u}_{v}\tilde{u}_{y}+2(\tilde{u}_{v}\tilde{v}_{y}+\tilde{u}_{y}\tilde{v}_{v})+2\tilde{x}_{v}\tilde{x}_{x}+2\tilde{y}_{v}\tilde{y}_{x} \end{array}$$

Good Luck!

equations:

Instead: analyze the Killing vector fields!

By analyzing the Lie algebra of Killing fields: every diffeo φ between

$$g = \tilde{H}(\tilde{u}, \tilde{x}, \tilde{y})d\tilde{u}^2 + 2d\tilde{u}d\tilde{v} + d\tilde{x}^2 + d\tilde{y}^2$$

$$\tilde{g} = H(u, x, y)du^2 + 2dudv + dx^2 + dy^2$$

has to be of the following form, for some a, b, c and f(x), g(u), h(u):

$$\begin{split} \tilde{u} &= (u+a)/c \\ \tilde{x} &= x\cos(b) + y\sin(b) + g(u) \\ \tilde{y} &= -x\sin(b) + y\cos(b) + h(u) \\ \tilde{v} &= c[v-x(\cos(b)g'(u) - \sin(b)h'(u)) \\ &-y(\sin(b)g'(u) - \cos(b)h'(u)) - f(u)] \end{split}$$

(1960) Jordan, Ehlers, Kundt, based on Robinson

Table of Contents

1 Spacetimes

- 2 Observables
- 3 The Proof



Canonical Quantization

Step 1: Find complete set of observables.



Step 2: promote them to an algebra of operators on a Hilbert space \mathcal{H} .



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G-observables where G has nice representation theoretic properties.

The Borel reduction hierarchy



A classification problem (X, E) is an equivalence relation E on Polish X

 $(X, E) \leqslant (\widetilde{X}, \widetilde{E})$ iff (X, E) Borel reduces to (Y, F)iff there exists Borel $r: X \to Y$ so that $xEx' \iff r(x)Fr(x')$

Problem. Place (S, \simeq_{diff}) in the Borel reduction hierarchy



Problem. Place (S, \simeq_{diff}) in the Borel reduction hierarchy



${\sf Th} \alpha {\sf nk}$ you!