Epistemic Logic for verifying runtime verification communication protocols

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In this work

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Jasmine Xuereb

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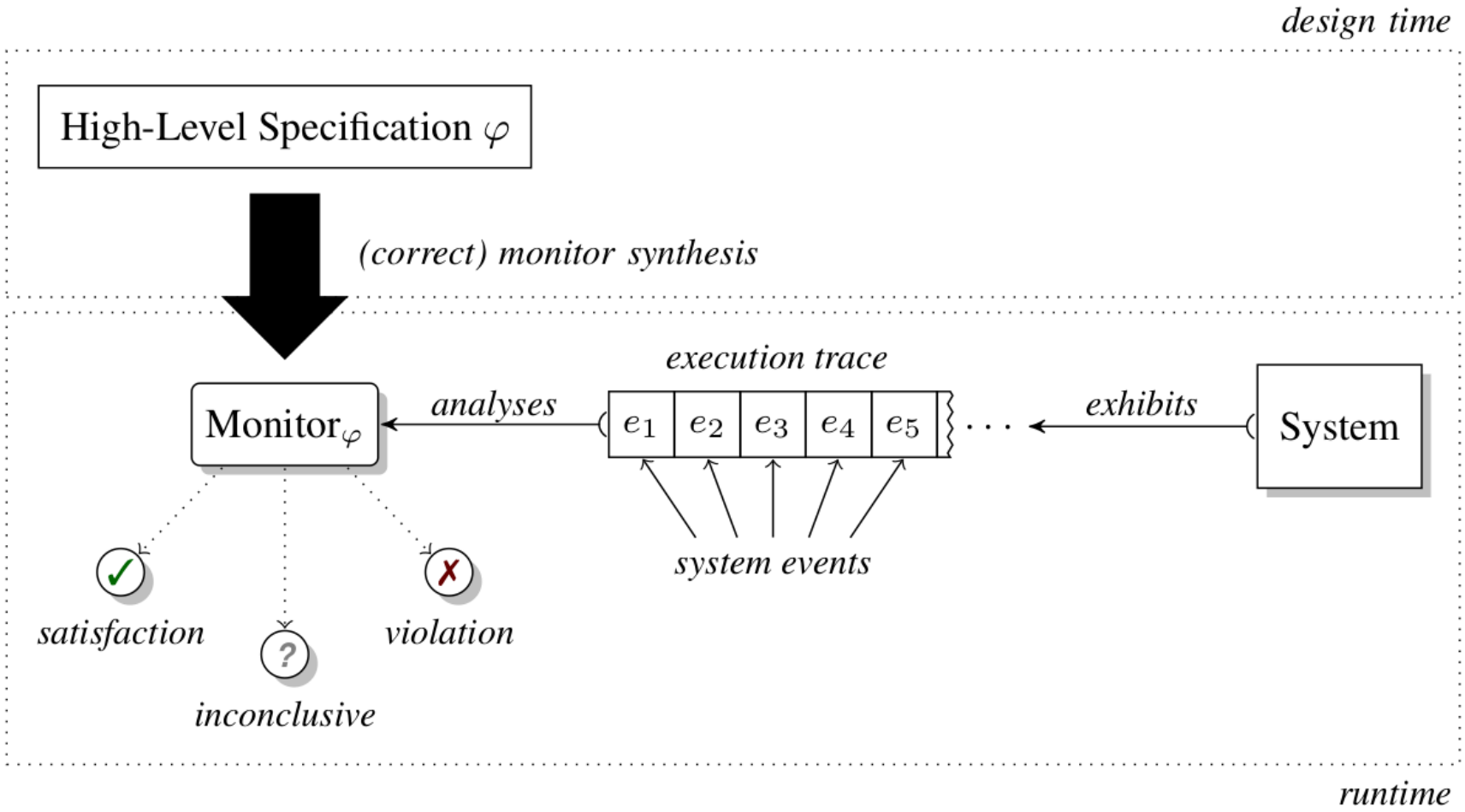
What is this about?



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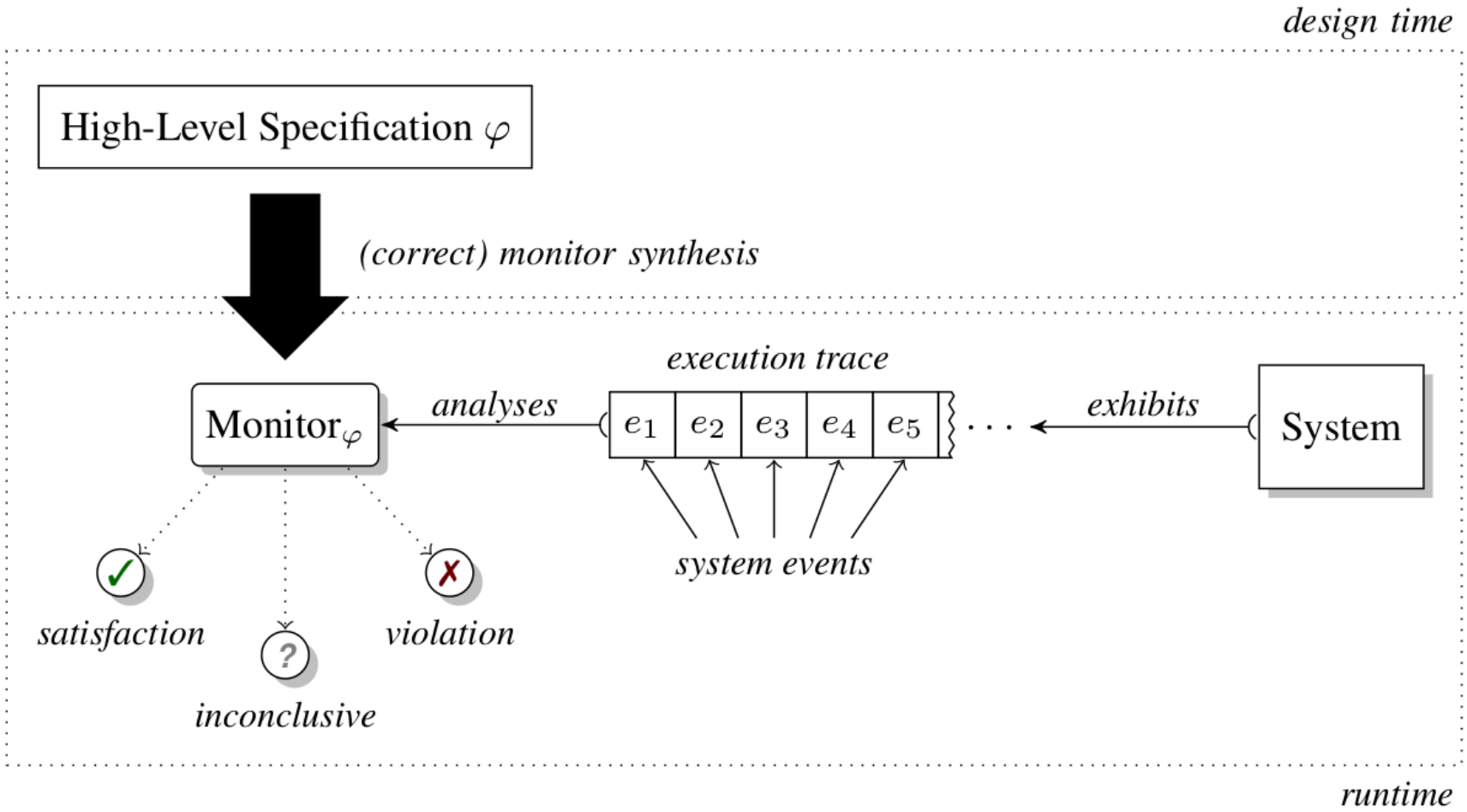

How about monitoring a global property over many systems/components/agents?

Aspects of the problem

- Stating global properties - what does “now” mean?.
- Tackling asynchronous components (trace collection, local clocks).
- Processing **many** traces at runtime.

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Logic | Parallel Setup | **Monitoring Setup**

The Logic: $Hyper^1$-sHML

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\begin{array}{llllll}
\varphi ::= \exists_\pi \varphi & \mid \forall_\pi \varphi & \mid \varphi \wedge \varphi & \mid \varphi \vee \varphi & \mid \psi \\
\psi ::= \mathtt{tt} & \mid \mathtt{ff} & \mid [A]\psi & \mid \langle A \rangle \psi & \\
\quad \mid \psi \wedge \psi & \mid \psi \vee \psi & \mid \max x.\psi & \mid \min x.\psi & \mid x,
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Example: The formula

$$\forall_\pi [a]\mathtt{ff} \sqcap \exists_\pi [b](max\ x.([a]\mathtt{ff}\ \wedge\ [b]x))\ ,$$

over $\textsc{Act}\ = \{a, b\}$, means that none of the traces start with a, and $b^\omega \in T$.

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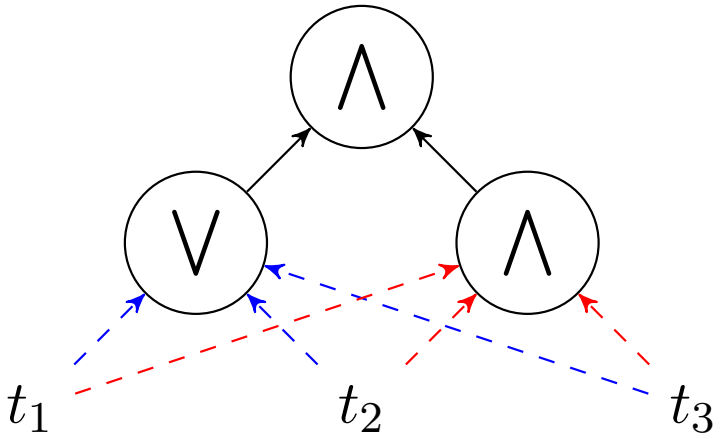

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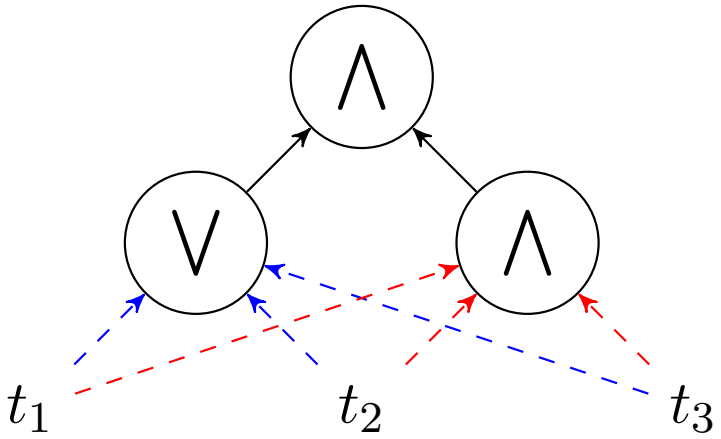

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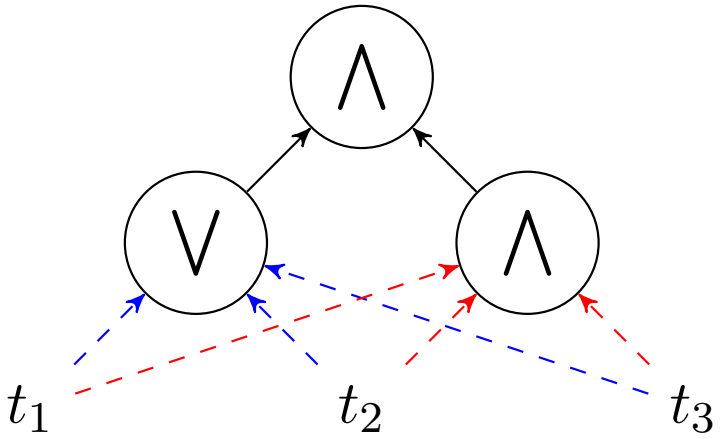

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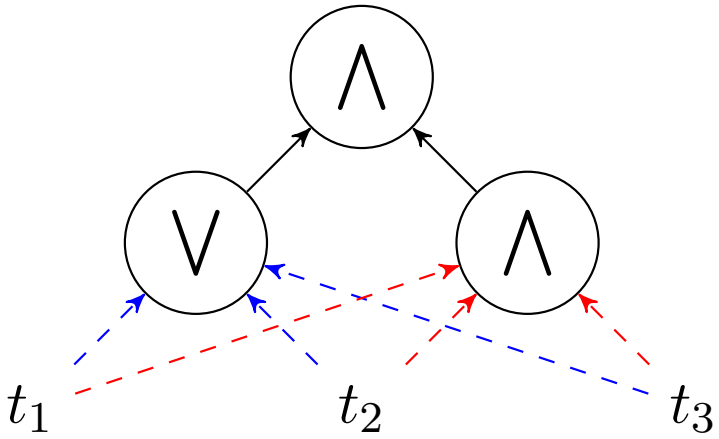

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Instead: Syntax!

$$M \in C\textsc{mon} ::= \bigvee [m]_k \mid \bigwedge [m]_k \mid M \vee M \mid M \wedge M$$

$$m ::= yes \mid no \mid end \mid a.m \mid m + n \mid rec\ x.m \mid x$$

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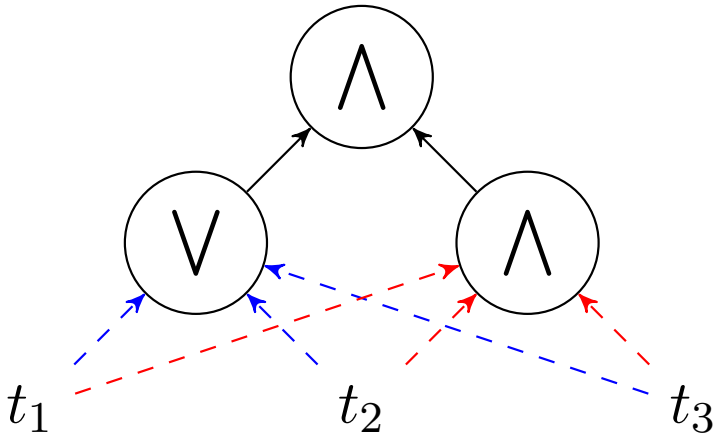

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How do we go from syntax to circuits?

Monitor semantics:

$$\frac{s[m_{[i]}] = yes}{s \to s[^{yes}/\bigvee[m]_k]} \qquad \frac{s[m_{[i]}] = no}{s \to s[\bigvee[m]_k \backslash i]} \qquad \frac{s[m_{[i]}] = end}{s \to s[\bigvee[m]_k \backslash end_i]}$$

$$\frac{s[\bigvee[m]_k] = 0}{s \to s[^{no}/\bigvee[m]_k]} \qquad \frac{s[\bigvee[m]_k] = 2^k}{s \to s[^{end}/\bigvee[m]_k]}$$

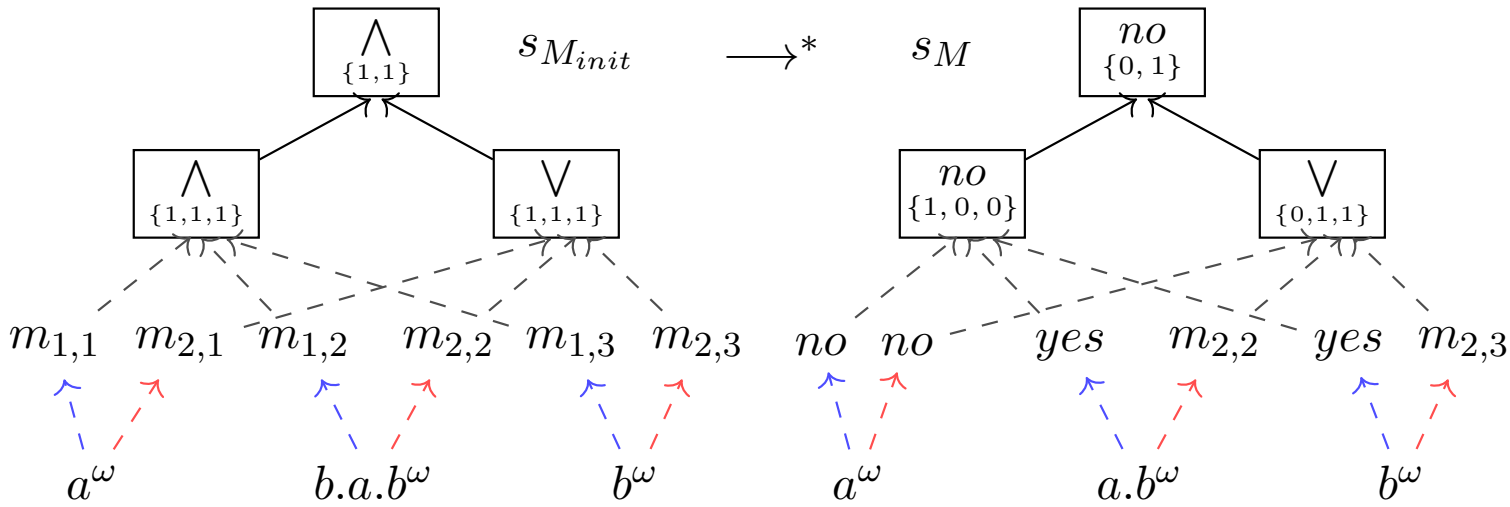
Instrumentation:

$$\frac{m \xrightarrow{\tau} m'}{m \triangleleft t \xrightarrow{\tau} m' \triangleleft t} \qquad \frac{m \xrightarrow{a} m'}{m \triangleleft a.t \xrightarrow{a} m' \triangleleft t} \qquad \frac{\forall j \in \{1, \ldots r\},\ m_{j[i]} \triangleleft t \xrightarrow{a} m'_{j[i]} \triangleleft t'}{s \triangleleft (\overrightarrow{m} \triangleleft T) \to s \triangleleft (\overrightarrow{m}[m'_{j[i]}/m_{j[i]},\ \forall j] \triangleleft T[t'/t])}$$

$$\frac{s \to s'}{s \triangleleft (\overrightarrow{m} \triangleleft T) \to s' \triangleleft (\overrightarrow{m} \triangleleft T)} \qquad \frac{s \triangleleft (\overrightarrow{m} \triangleleft T) \to s \triangleleft (\overrightarrow{m}[v/n_{j[i]}] \triangleleft T[t'/t])}{s \triangleleft (\overrightarrow{m} \triangleleft T) \to s[v/g_{m_{j[i]}}] \triangleleft (\overrightarrow{m}[v/n_{j[i]}] \triangleleft T[t'/t])}$$

An example

Formula: $\forall_\pi[a]\mathtt{ff} \sqcap \exists_\pi[b](max\ x.([a]\mathtt{ff}\ \wedge\ [b]x))$.
Monitor:



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And we proved we **can** have these.

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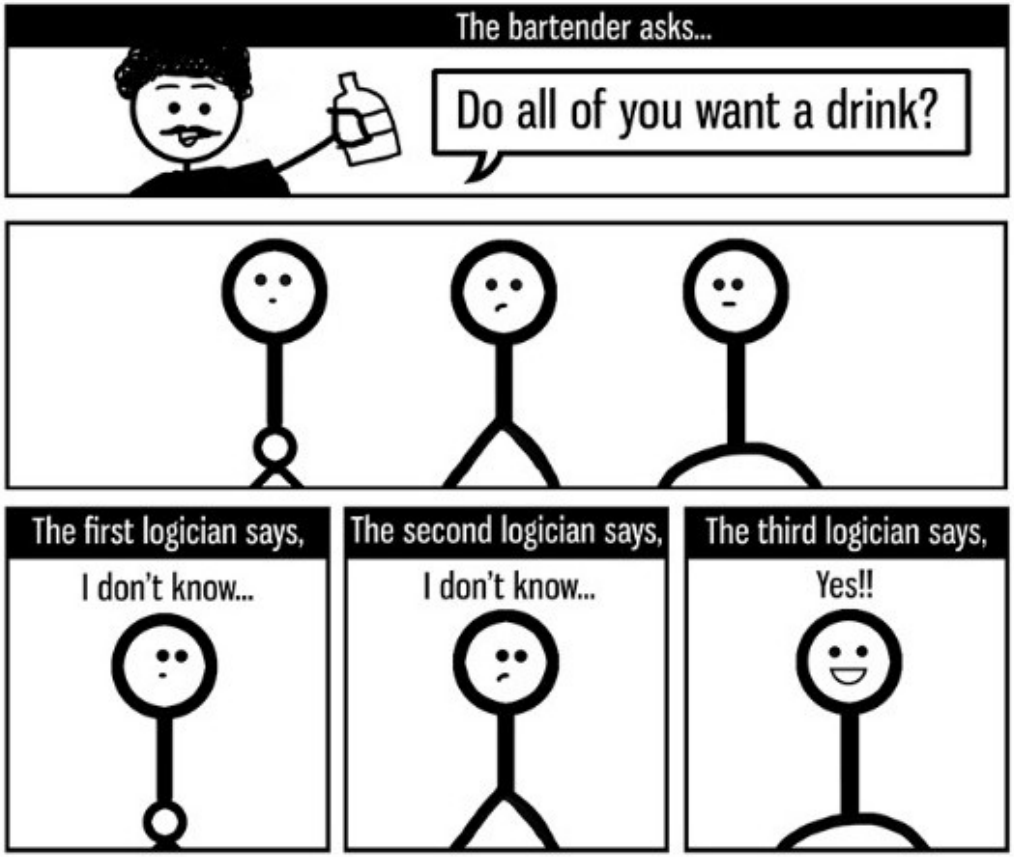
Three Logicians walk into a bar



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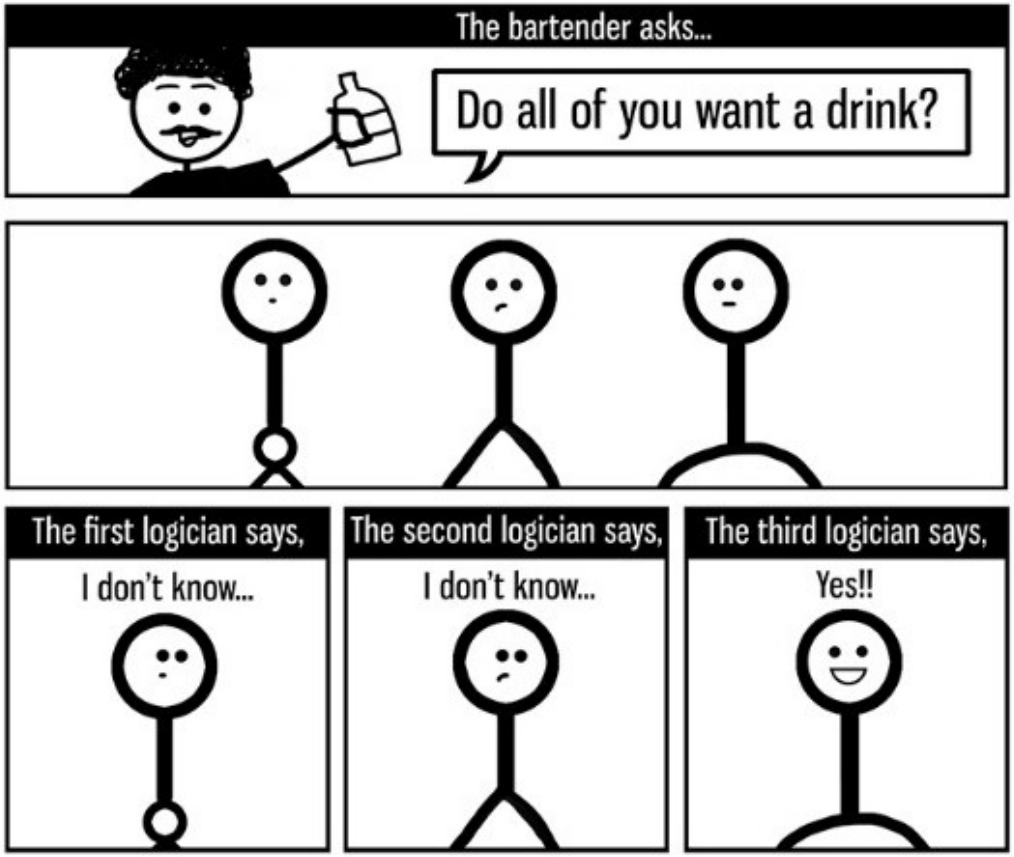

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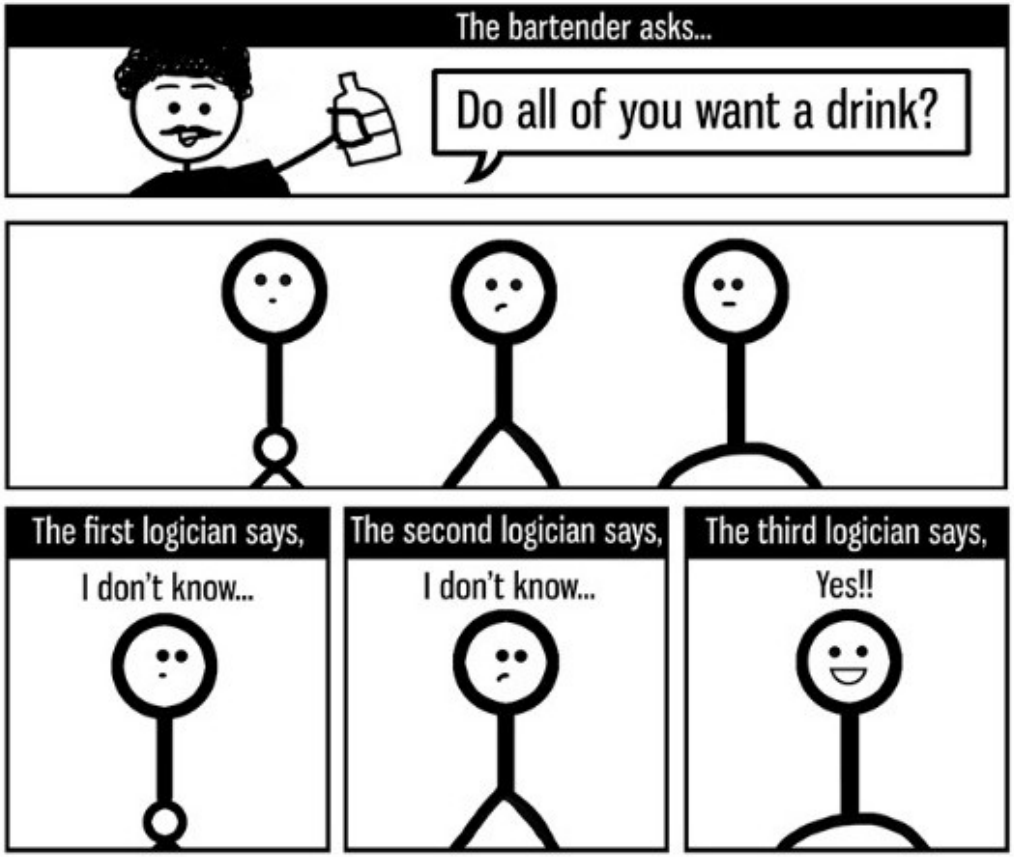

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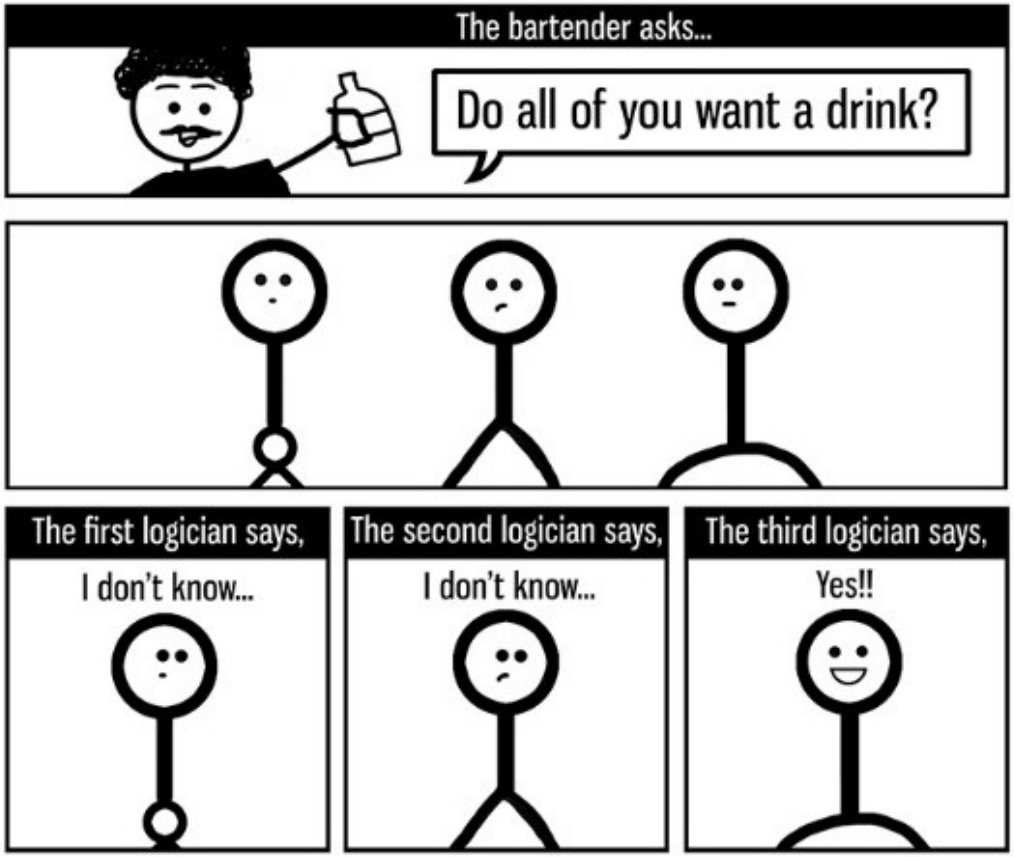

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We want:

- Use this (correct) proofs to extract good monitoring procedures.
- Hopefully extract them automatically (proofs and protocols).

Lets get our hands dirty!

Definition (Multi-agent epistemic logic)

For a set of agents $\mathcal{A}$, a formula ϕ in the multi-agent modal logic is defined as:

$$\phi ::= \top \quad | \quad \bot \quad | \quad p \quad | \quad \neg\phi \quad | \quad \phi \wedge \phi \quad | \quad K_i\phi \quad | \quad C_G\phi$$

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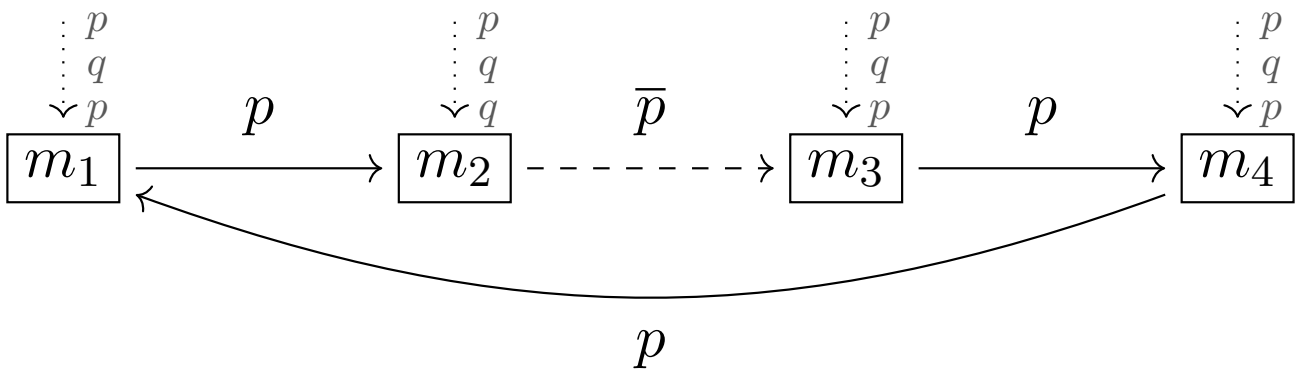
- This logic can help us express the ***state*** of knowledge between agents in some distributed setup.
- Evolution of knowledge of agents (monitors) coming soon.

A communication protocol



A Communication Protocol for

$$\varphi = \forall\pi\forall\pi' max\ x([p_\pi, \overline{p}_{\pi'}]\mathtt{ff} \wedge [p_\pi, p_{\pi'}]x \wedge [\overline{p}_\pi, \overline{p}_{\pi'}]x)\ ,$$

i.e. "all traces agree on p."

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Now what? Automate proofs (tableaus), use logic that expresses the *acquisition of knowledge*, even more success.

Thank you for your attention!

Questions?